# Connected and Automated Vehicle Technology for Trucking Industry

Southwest Research Institute®

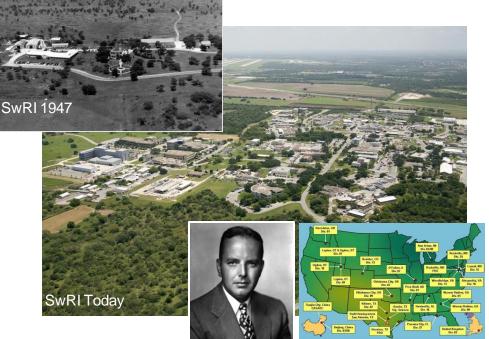
Eric Thorn, Ph.D. – Manager R&D

TennSMART Fall Meeting November 5, 2019



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### About Southwest Research Institute®



### **Organizational Characteristics**

- Independent and nonprofit [501(c)(3)]
- Revenue provided by R&D contracts
- Broad technological and scientific capabilities
- Decentralized organization
- Internal research encouraged
- Unique Client-Oriented intellectual property policy

### **10 Operating Technical Divisions**

- Applied Physics
- Applied Power
- Intelligent Systems
- Mechanical Engineering
- ✤ Engines, Emissions, and Vehicle Research
- ✤ Fluids and Lubricants Research
- Signal Exploitation and Geo-location
- Space Science and Engineering
- Geosciences and Engineering
- Chemistry and Chemical Engineering

### About SwRI

- ESTABLISHED: 1947
- ✤ STAFF: >2,600
- GROSS REVENUE FY2018: >\$584M
- FY18 Projects: >5,000
- CAMPUS: ~4.86 km2 (1,200 Acres) in San Antonio, TX
- ✤ LABS/OFFICES: > 2.3M ft<sup>2</sup>
- Over 1,300 Patents; 43 R&D 100 Awards
- FY18 IR&D: \$6.8M, 179 projects

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## Commercial Vehicle Infrastructure Integration (CVII) Program

### Purpose

- Develop and test Connected Vehicle technologies that will enhance Commercial Vehicle security, mobility, and safety.
  - Wireless Roadside Inspection
  - Traveller Advisories
  - Probe Data
  - Driver Credential Identification
  - Maintenance to Commercial Vehicle Communications
  - Safe-to-Merge, Safe-to-Pass, Blindspot Warning, Tailgate Warning
  - Railroad Grade Crossing Warning

### Results

- Team: Volvo, SwRI, Kapsch TrafficCom, Booze Allen Hamilton, Cambridge Systematics, Fitzgerald & Halliday
- Was demonstrated at ITS World Congress in October 2011 in Orlando, FL.
- Recognized as Project of the Year by ITS NY



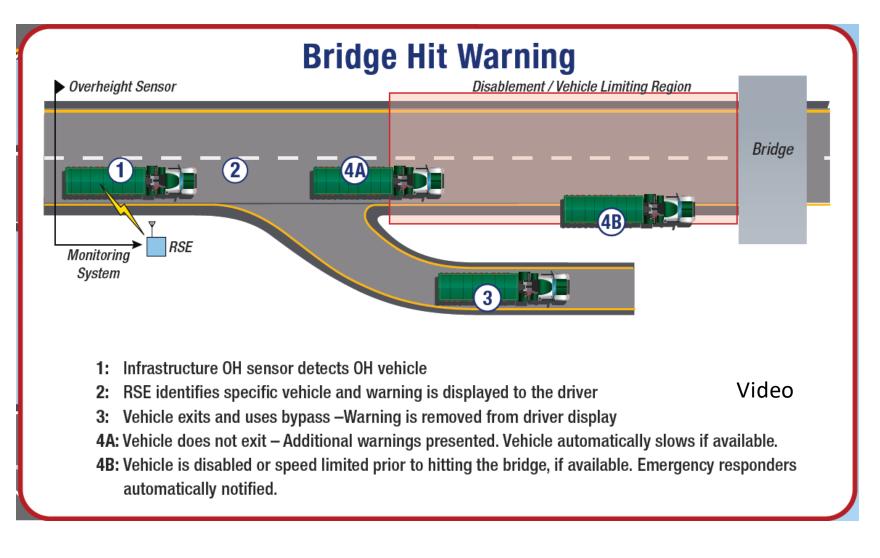


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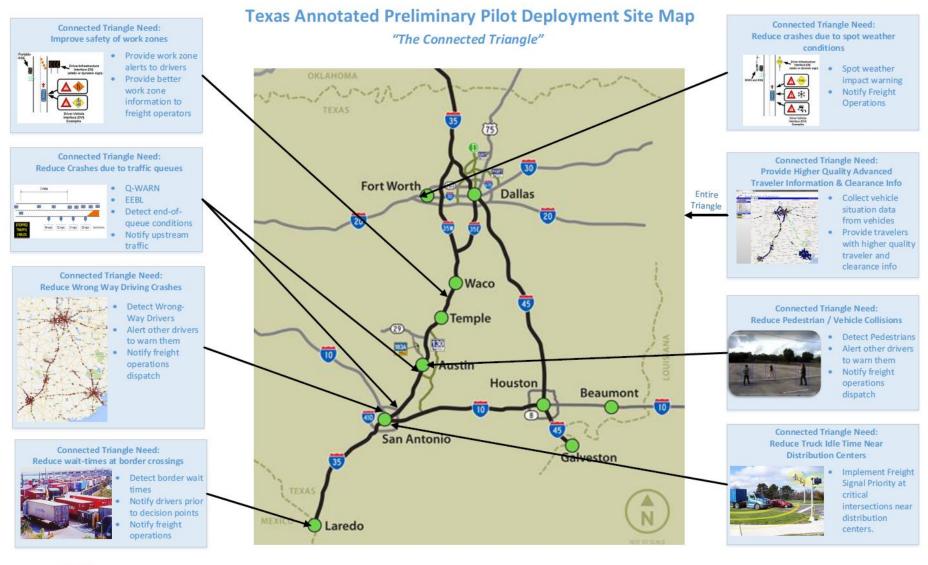
## **Over-height Vehicle Detection & Warning**





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## **Texas Connected Freight Corridor**





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## **CV Technology for Improved Fuel** Efficiency

- Goal of reducing vehicle energy consumption by at least 20%
- Leverage connectivity, automation, and model predictive control

- Traffic Simulator
- Traffic simulator feeds HIL simulation

Signal Phase and Timing Road type/ grade, Vehicles speed, ...

#### Co-optimized Vehicle & Powertrain Control

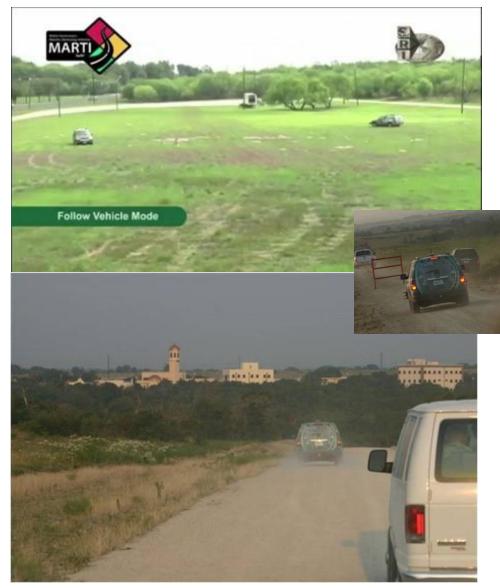
CAV on Chassis Dyno

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## Platooning / Cooperative Convoy System

- UGV actively participating in convoy
- Variable lateral offsets and longitudinal spacing
- Vehicle reordering in convoy
- Autonomous UGV lead through urban environment interacting with traffic and pedestrians
- Convoy separation and rejoining



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### **Automated Trailer Docking**







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## Thank You!

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